

## **Engineering Mathematics-I**

Subject Code	: 14MAT11	IA Marks	: 25
Hours/Week	: 04	Exam. Hours	: 03
Total Hours	: 50	Exam. Marks	: 100

### **Course Objectives**

To enable students to apply knowledge of Mathematics in various engineering fields by making them to learn the following:

- $n^{\text{th}}$  derivatives of product of two functions and polar curves.
- Partial derivatives, indeterminate form and jacobian.
- Vectors and Curve tracing.
- Reduction formulae; First order differential equations.
- Solution of system of equations and quadratic forms.

### **Module –1**

#### **Differential Calculus -1:**

Determination of  $n^{\text{th}}$  order derivatives of Standard functions - Problems. Leibnitz's theorem (without proof) - problems.

**Polar Curves** - angle between the radius vector and tangent, angle between two curves, Pedal equation for polar curves. Derivative of arc length - Cartesian, Parametric and Polar forms (without proof) - problems. Curvature and Radius of Curvature – Cartesian, Parametric, Polar and Pedal forms and problems. **10hrs**

### **Module –2**

#### **Differential Calculus -2**

Taylor's and Maclaurin's theorems for function of one variable(statement only)- problems. Evaluation of Indeterminate forms.

**Partial derivatives** – Definition and simple problems, Euler's theorem – problems, total derivatives, partial differentiation of composite functions, Jacobians-definition and problems, extreme values of functions of two variables . **10hrs**

### Module –3

#### Vector Calculus:

Derivative of vector valued functions, Velocity, Acceleration and related problems, Scalar and Vector point functions, Gradient, Divergence, Curl, Solenoidal and Irrotational vector fields. Vector identities -  $\text{div}(\Phi \mathbf{A})$ ,  $\text{curl}(\Phi \mathbf{A})$ ,  $\text{curl}(\text{grad } \Phi)$ ,  $\text{div}(\text{curl } \mathbf{A})$ .

Differentiation under integral sign using Leibnitz rule with constant and variable limits.

**Curve Tracing** - General rules to trace Cartesian, polar and parametric curves. **10hrs**

### Module- 4

#### Integral Calculus:

Reduction formulae  $\int \text{Sin}^n x dx$ ,  $\int \text{Cos}^n x dx$ ,  $\int \text{Sin}^m x \text{Cos}^n x dx$  (m and n are positive integers), evaluation of these integrals with standard limits (0 to  $\pi/2$ ) and problems.

#### Differential Equations:

**Solution of first order and first degree differential equations** – Exact, reducible to exact and Bernoulli's differential equations. **Applications**- orthogonal trajectories, Newton's law of cooling, flow of electricity, laws of decay and growth. **10hrs**

### Module –5

#### Linear Algebra

Rank of a matrix by elementary transformations, solution of system of linear equations - Gauss-elimination method, Gauss-Seidel method and L-U decomposition method.

Linear transformation, diagonalisation of a square matrix, Quadratic forms, reduction to Canonical form by orthogonal transformation, Rayleigh's power method to find the largest Eigen value and the corresponding Eigen vector. **10hrs**

#### Course Outcomes:

On completion of this course, students are able to

- Use partial derivatives to calculate rates of change of multivariate functions.
- Analyze position, velocity, and acceleration in two or three dimensions using the calculus of vector valued functions.
- Trace the curves which are useful in applications of integration in finding the length, area and volume.

- Recognize and solve first-order ordinary differential equations, model simple electrical circuits, projectile motion and Newton's law of cooling and laws of decay and growth, and
- Use matrices, determinants and techniques for solving systems of linear equations in the different areas of Linear Algebra.

**Scheme of examination:**

- **Two full questions (with a maximum of four sub questions) of twenty marks each to be set from each module. Each question should cover all contents of the respective module.**
- **Students have to answer five full questions choosing one full question from each module.**

**Text Books:**

1. B.S. Grewal, "**Higher Engineering Mathematics**", Khanna publishers, 42<sup>nd</sup> edition, 2013.
2. Erwin Kreyszig, "**Advanced Engineering Mathematics**"-Vol-I & II, Wiley, 2013

**Reference Books:**

1. B.V. Ramana, "**Higher Engineering Mathematics**", Tata Mc Graw-Hill, 2006
2. N.P.Bali and Manish Goyal, "**A text book of Engineering mathematics**", Laxmi publications, latest edition.
3. H.K. Dass and Er. RajnishVerma, "**Higher Engineerig Mathematics**", S.Chand publishing, 1<sup>st</sup> edition, 2011.